Cultivating Computational Thinking through the integration of Art and Educational Robotics

Maria Tzelepi¹, Kyparisia Papanikolaou^{1,2}, Nafsika Pappa¹, Eleni Zalavra¹, Nikolaos Kladis³, Spyros Siakas¹

mtzelepi@uniwa.gr, kpapanikolaou@aspete.gr, npappa@uniwa.gr, ezalavra@uniwa.gr, nikos.kladis@outlook.com.gr, sthsiakas@uniwa.gr

1 University of West Attica
2 School of Pedagogical and Technological Education
3 National and Kapodistrian University of Athens

Abstract

This paper introduces the interdisciplinary approach integrated into the FERTILE Design Methodology (FDM) that blends Educational Robotics (ER) and Arts to cultivate computational thinking (CT) skills in a blended learning context. The paper demonstrates how ER and Arts can be combined to create interdisciplinary learning experiences through the presentation of two exemplar projects. Both projects guide students through a series of five (5) steps—Understanding the Challenge, Generating Ideas, Formulating the Solution, Creating the Solution, and Evaluating the Solution—ensuring the integration of both disciplines while fostering CT skills cultivation such as abstraction, decomposition, pattern recognition, algorithmic thinking, and evaluation. Insights from educators involved in designing and implementing these projects highlight the methodology's potential to promote interdisciplinary collaboration and student CT skill development. This paper provides practical guidance for educators seeking to implement Artful ER projects with their students, emphasizing the potential of interdisciplinary approaches to enrich student learning.

Keywords: computational thinking, educational robotics, interdisciplinarity, art

Introduction

Integrating computational thinking (CT) in education is increasingly recognized as essential for preparing students for the complexities of the modern world. CT equips students with critical problem-solving skills, enabling them to break down complex tasks, recognize patterns, and develop efficient solutions. These skills are not only vital for technology and engineering but are also applicable across various disciplines and real-world scenarios. Research indicates that developing CT skills enhances students' analytical abilities and prepares them for a wide range of professions (Wing, 2010; Grover & Pea, 2013). Combining educational robotics (ER) and arts offers a unique and powerful approach to enhancing CT skills. ER provides hands-on, practical experiences that make abstract CT concepts tangible and accessible (Fronza et al., 2017; Chookaew et al., 2018; Jawawi et al., 2022). Robotics activities engage students in the design, construction, and programming of robots, which helps them apply CT in real-world contexts (Bers, 2018). These activities become more engaging and creative when paired with art, fostering a deeper connection to the material. Artistic activities encourage creativity, innovation, and critical thinking, which are core components of CT (Peppler & Glosson, 2013; Vacca et al., 2021). This interdisciplinary approach encourages students to apply CT principles in innovative ways, integrating ER and Art perspectives to solve problems.

In this paper, we present exemplar interdisciplinary projects following the FERTILE Design Methodology (FDM), a structured framework that guides educators in combining ER and Arts to create a new context for cultivating students' CT skills. Thus, the FDM aims at creating engaging learning experiences that promote deeper understanding of CT.

The exemplar interdisciplinary projects included in the paper showcase insights into how intentional and structured integration of ER and Arts can enhance students' learning experiences. Our aim is to offer valuable guidance for educators in designing and implementing interdisciplinary projects, now on entitled "Artful ER projects", that situate CT in a new domain based on the synthesis of ER and Arts ones. Additionally, the paper provides insights from educators who designed and implemented the projects, into the effectiveness of the FDM steps in achieving the intended interdisciplinary and CT skill cultivation goals.

Promoting CT in an interdisciplinary context combining ER with Arts

ER is a valuable tool for promoting CT in students (Istikomah, 2018) as it provides a creative context that facilitates learning of basic programming principles including sequencing, algorithms, loops, generalization, decomposition, and debugging (Ching, 2023; Piedade, 2020; Souza et al., 2021). In this line, the Creative Computational Problem Solving model (CCPS) (Chevalier et al., 2020) combines two primary approaches: the structured problem-solving processes inherent in CT and the iterative, exploratory nature of creative problem-solving. The CCPS model is structured around iterative phases designed to facilitate transitions between understanding the problem, generating ideas, formulating the robot's behavior, programming the robot's behavior, evaluating the final solution and one more phase which describes a brief disengagement period for the problem solver (Off task behavior).

The FDM is based on the CCPS model, aiming to structure students' activity around ER and Arts in a blended learning context and to facilitate enactment with students in real school settings. In particular, artistic expression and creative problem-solving across multiple domains such as ER and Painting or Music or Performing Arts, or Visual Arts, is promoted by integrating ER with Arts into four project categories: Programming Robots to Create Art, Programming Robots to Perform Art, Creating Artful Robots, and Programming Robots to Respond to Artful Triggers. Thus, the FDM steps — Understanding the Challenge, Generating Ideas, Formulating the Solution, Creating the Solution, and Evaluating the Solution — reflect an adaptation of the CCPS model's iterative problem-solving phases. This ensures that students engage in a structured yet flexible framework that fosters CT skills through both ER and Arts, enhancing their overall learning experience.

For instance, in a project of the "Programming Robots to Create Art" category, students might program and construct a robot capable of creating a painting by moving a brush on a canvas. In a project of "Programming Robots to Perform Art" category students may program robots to dance alongside humans. Also, in a project of the "Creating Artful Robots" category students may emphasize on both aesthetic design and functionality, promoting creativity in robot building. Finally, in a project of the "Programming Robots to Respond to Artful Triggers" category students might program a robot to change its movements in response to music or lighting changes.

Moreover, the use of ER simulators aims at enabling students to experiment with programming by developing code, identifying errors, and refining their solutions in a controlled setting before implementation, providing students with the flexibility to practice and learn at their own pace, both in the classroom and at home.

Lastly, the FDM promotes CT skills cultivation in both ER and Art subjects in a way that facilitates enactment with students in real school settings. Educators of both disciplines, ER

and Arts, design together a project to be implemented in both courses considering that students, through the various steps, must develop a common Artful-ER product/solution. They also have in mind that apart from the learning outcomes of their subject, they should cultivate CT skills. These skills act as the common language allowing educators to build a common design mindset. The skills that are currently under exploration are based on Selby and Woollard's (2013):

- Abstraction involves identifying the key elements of a problem while ignoring irrelevant
 details. It helps students focus on the essential components of the challenge, making
 it easier to understand and solve.
- Pattern recognition involves identifying similarities, regularities, and recurring patterns within the problem domain. It enables students to draw connections between elements and use these patterns to inform their solutions.
- Decomposition is necessary for breaking down complex problems into smaller, more manageable parts. This competency is crucial for tackling large projects by addressing each component individually.
- Algorithmic thinking is the ability to develop step-by-step instructions or sequences of actions to solve a problem. It focuses on creating efficient and logical solutions.
- Evaluation involves assessing and analyzing a solution's effectiveness, efficiency, and quality. It critically examines the outcomes and determines whether they meet specific objectives or criteria.

The FDM guides educators to design Artful ER projects through a structured, step-by-step process as follows (see Figure 1):

- 1. The first step, "Understanding the Challenge" engages students by introducing them to the project's objectives and helping them grasp the key elements of the challenge/problem they need to solve. As students need to identify the essential components of the challenge, approaching it from both the ER and Arts perspectives, abstraction and decomposition are CT skills that are cultivated in this and the next step. In some cases, pattern recognition is a skill that may also be cultivated for understanding particular challenges, including identifying a pattern.
- 2. In the second step, "Generating Ideas" students brainstorm and develop initial ideas related to the challenges identified in the previous step, stimulating their creativity and problem-solving skills through hands-on practice and simulations.
- 3. The third step, "Formulating the Solution" involves detailed planning and algorithm development, ensuring students have a clear roadmap for implementing their ideas from both the ER and Arts perspectives. Algorithmic thinking is emphasized during the Formulating and Creating the Solution steps, where students design, construct and program solutions, following their ideas generated in the previous step.
- 4. During the fourth step, "Creating the Solution" students bring their designs to life by constructing, programming and synthesizing the final product of the project as the solution to the initial challenge.
- 5. The final step, "Evaluating the Solution" allows students to present their solution, receive feedback based on criteria that emerge from the previous steps, and reflect on their work and that of their peers. Evaluation is an ongoing process through the project implementation that cultivates students' evaluation skills, with students continuously testing and refining their ideas/solutions based on feedback and performance assessments.

As described above, the FDM steps help students cultivate a set of CT skills that are applicable across both Art and ER disciplines, as well as in real-world scenarios.

Below, two case studies of exemplar Artful ER projects based on the FDM are presented and discussed.



Figure 1. The CT skills that students cultivate through the FDM steps

Case Study 1: The "RoboAnimation" Artful-ER project combining ER and Animation

This project draws on a fundamental principle in animation that enhances the impact and realism of a character's actions by creating a sense of anticipation. This principle builds up tension or expectation before a significant action, engaging the audience and increasing emotion in the scene.



Image 1. Students engage in stop-motion activity during the "Generating Ideas" step

The challenge: To initiate the learning process, the teacher prompts students to actively engage in storytelling activities centered around a robot character.

As a challenge, the teacher provides an initial story framework, and students are tasked with developing this story further while ensuring that the main goal — programming the robot to move with anticipation — is met. For this, they must construct a robot to serve as the main character and program its anticipation-based movements. Students construct the robot hero

based on its characteristics, generate ideas to develop the story, and, if necessary, set up an appropriate scene to bring their story to life.

The project falls under the category of "programming robots to perform art" targeting upper primary students. The total duration of the project is 7 hours, during which students engage in visual arts, particularly animation, to learn about speed, movement, and pause, as basic elements of anticipation. Regarding ER, students focus on constructing a robot featuring one or two motors and programming it to control direction and speed. During the project implementation, we used the NEZHA Inventor's kit for Micro:bit, with Makecode for Micro:bit serving as both the programming environment and the simulator. The construction elements included actuators such as two motors and one servo, whilst no sensors required. The project could be expanded for secondary education by incorporating other robotic platforms such as Arduino. In this case, students could take on additional challenges such as designing and building custom robot components or incorporating sensors to enhance interactivity. The storytelling and performance elements can also be adapted to suit the interests, knowledge and skills of students, potentially integrating aspects of digital storytelling.

Students follow the project steps to reach a solution to the challenge proposed (see also Table 1 for more details):

In the Understanding the Challenge (UND) step, the teacher presents the challenge and its objectives to the students introducing them to an initial story featuring a robot-hero with anticipation movements. The students identify key patterns and underlying concepts to understand the context and prepare for the challenge.

Then, in the Generating Ideas (GEN) step, the students brainstorm and develop initial ideas for their robot-hero. In the ER class, they practice with robot construction and stopmotion animation to apply anticipation techniques. In the Arts class, they practice storytelling and create visual elements for their project.

Next, in the Formulating the Solution (FORM) step, the students formulate detailed plans and algorithms for their projects. They create step-by-step instructions to solve smaller tasks, ensuring their robot's behavior aligns with the story. They select materials and plan the construction of the story scene, developing a clear roadmap for implementation.

Next, in the Creating the Solution (CRE) step, the students implement their designs, constructing the physical robot and setting up the scene as planned. They program the robot themselves using the instructions they developed earlier and make necessary adjustments to ensure correct execution. This hands-on phase allows them to transform their plans into tangible outcomes.

Evaluating the Solution (EVA) In the final step, students discuss, test and refine their solution to the initial challenge fostering a deeper understanding and improvement of their projects.

Table 1. Steps and CT Skills corresponding cultivated during the "RoboAnimation"

project	
The RoboAnimation Proje	ect
FDM	CT skills

The RoboAnimation Project				
FDM Arts	Arts	Robotics	CT skills cultivated	
SIEFS			Arts	ER
STEP 1:	The students analyze the initial	The students examine	Abstra	
Understan	story featuring a robot hero,	paradigms of robots, their	ction,	
Understan	describing the robot's character in	motors, and the range of	Patter	

ding the Challenge	the given story, its capabilities (Decomposition) and focusing on the essential elements of the story (Abstraction). The students identify specific patterns in the robot-hero's movements (Pattern	possible movements to be able to describe the robothero of their story (Decomposition).	n recogn ition	
	recognition) reflecting anticipation.	Charles in annual color	D-11	
	The teacher introduces the students to the stop-motion environment, where they put the	Students in groups select the materials for the construction of their robot- hero (Decomposition)	Patter n Abstra recogn ction ition	
STEP 2: Generatin g Ideas Frobot to act according to their story (Decomposition) employing anticipation techniques (Pattern Recognition) (see Image 1).		based on the capabilities of the robot-hero (Abstraction). Through hands-on practice and experimentation, the students learn about the concept of speed.	Decomposition	
	Inspired by the activities with sto solutions to meet the challenge's req	=		
STEP 3: Formulati ng the Solution	The students provide a verbal description of a) the movements that the robot will perform and the corresponding sequence of instructions in natural language, and b) the decoration plans for the robot (if applicable) (Algorithmic Thinking, Decomposition). After that they program the robot's behavior in the simulator (Algorithmic Thinking).	The students search for materials that are suitable for constructing the scene of the story, identify objects that are of appropriate shape and size for the robot to interact with (Decomposition), and formulate clear instructions for the robot's actions (Algorithmic Thinking).	Decomposition, Algorithmic thinking	
STEP 4: Creating the Solution	The students program the physical robot, and make various accommodations (Algorithmic Thinking).	Students use various materials to set up the scene as they decided in the previous step (Algorithmic Thinking).	Algorithmic thinking	
STEP 5: Evaluatin g the solution	Students present their final story at classmates' stories according to the r the process and evaluate their wo Depending on the final result, they make appropriate corrections (Evaluate)	nd, in turn, try to guess their robot's behavior. They discuss ork and the work of others. return to a previous phase to	Evaluation	

Case Study 2: The "Travel to Mars" Artful-ER project combining ER and Theatre

The challenge: Through a role-playing game, students engage in "traveling" to Mars to carry out a mission. This mission aims to collect evidence about a rover that landed on Mars some months ago but no longer sends a signal. The students will be the crew members, and the robots will be the spaceship engines.

This project falls under the category of "programming robots to perform art" targeting lower primary students. The project lasted 6 hours and Beebots was the robotic technology used. This project could also be implemented in upper primary classes with another technology of pre-built robots, such as Edison or Thymio, which require higher programming skills. It could also be implemented in secondary education with robot engines built by the students, such as Arduino, Micro:bit, Lego Spike, etc. In any case, the performance part would have to be differentiated to meet the needs/interests of the students.

Through the ER and Theatre classes, students will prepare to (a) simulate the trip going to Mars, (b) get evidence from the lost contact rover, and (c) then, when returning to Earth, analyze the evidence found and describe the trip experience.



Image 2: Travel to Mars project

The solution to the challenge is accomplished by following the project steps as follows (see also Table 2 for more details):

In the **Understanding the Challenge (UND)** step, the students discuss with the teachers the challenge of the project. They elaborate on the key elements of the challenge, aiming to identify sub-challenges, such as their role as crew members and the role of the robots in the story. In each subject (ER and Arts), they concentrate on the main tasks they have to do.

In the **Generating Ideas (GEN)** step, the students break down the tasks, brainstorm, and provide ideas about their accomplishment. In the ER class, they practice small missions with the robot simulator, and in the Theatre class, they get engaged with costume decoration ideas.

In the **Formulating the Solution (FORM)** step, the students experiment with solutions for the movements of crew members and robots. They create instructions to solve the smaller tasks.

In the **Creating the Solution (CRE)** step, the students try to find the optimum solution, apply it to accomplish the challenge, and make possible corrections. They travel to Mars, collect the evidence and return back to Earth.

In the **Evaluating the Solution (EVA)** step, using specific criteria, the students evaluate their performance as crew members and robots' performance as engines. They also reflect on the strong and the weak aspects of the mission.

Table 2. Steps and corresponding CT Skills cultivated during the "Travel to Mars" project

FDM STEPS	Arts	Arts Robotics		CT skills		
			cultivated			
			Arts	ER		
STEP 1:		The students focus on the role	Abstraction			
SIEP I:	of the robots as spaceship		Decomposition			

Understandi ng the Challenge	The students focus on their role as crew members (Abstraction). They distinguish the movement of their bodies according to whether they are on Earth or Mars (Decomposition).	engines (Abstraction). They consider various aspects related to robots (Beebots) acting as spaceship engines (movements, programming, synchronization with the crew members) (Decomposition).	Pattern Recognit ion	
STEP 2: Generating Ideas	They simulate their movement in different weather conditions on every planet (Pattern Recognition). Break down the challenge and provide ideas for specific aspects, such as team symbols, decorations for their "costumes," etc. (Decomposition). The students provide ideas for small artifacts related to these	Analyze the robots' movements (Decomposition). and practice with the simulator through small missions (Algorithmic Thinking).	Decomposition Pattern Algori Recognit thmic ion Thinki ng	
STEP 3: Formulating the Solution	aspects (Pattern Recognition). The students experiment with instructions for the crew members' movements (Algorithmic Thinking). Do small flight tests breaking down the crew members' movements (Decomposition).	Students practice with the physical robots to test the take- off and landing of the engines. They give instructions to the robots to move and spin (Algorithmic Thinking). They discuss with the teacher the concept of scale to compare their movements in steps to the robots' ones (Abstraction). To measure and correlate the scale, the students stand up and try to walk next to the robot(Decomposition).	Algorithmic Thinking Decomposition Decomp Abstra osition ction	
STEP 4: Creating the Solution	decided on (Algorithmic Thir Earth to Mars and from Ma possible evidence. During the	Students create a step-to-step solution for robots' moving (Algorithmic Thinking) and find the most efficient way to synchronize human steps with robot steps. y following the instructions they lking), completing the trip from rs to Earth, and gathering the trip, they address any problems the spaceship and the	Algorithmic Thinking Decomposition	
STEP 5: Evaluating the Solution	Students evaluate the compliance of the evidence found with the mission. They reflect on their experience through an interview with	Students assess whether the robots acted properly during the mission (Evaluation). They use a star rating worksheet to evaluate programming, synchronization	Evaluation	

the art teacher acting as a with the other engines and journalist their movements.

(Evaluation).

Educators' insights from the projects' design and implementation

To explore educators' experiences with the two Artful ER projects, we gathered insights from five educators — three involved in the 'RoboAnimation' Project (E1–E3) and two in the 'Travel to Mars' Project (E4–E5) (see Table 3). Using an instrument with three closed-ended and three open-ended questions, we collected initial evidence at the end of both projects. The closed-ended questions explore educators' perceptions of how well the FDM facilitated the design and implementation (see Table 3), while the open-ended questions aim to gain deeper insights into potential challenges, successes, and improvements experienced. (**Question 1:** "How did you find useful designing the project by a) following the particular steps' sequencing, and b) designing activities for each step?", **Question 2:** "Since the FDM aims to cultivate CT through the interdisciplinarity of Art and ER in a blended learning context, suggest changes/improvements in this direction.", **Question 3:** "What would you change in the Artful ER project design after the implementation experience?"

Table 3. Educators' perceptions of how well the FDM steps facilitate the design and implementation of Artful ER projects

Close-ended questions		Project 1		Project 2	
		E2	E3	E4	E5
Breaking down each step into individual activities was helpful for designing students' involvement in the project	3	5	5	4	5
Designing together activities for cultivating particular CT skills promoted mutual understanding of the disciplines involved.	0	5	5	5	5
The FDM supported me in understanding how to cultivate CT skills through the project.	5	5	4	5	5

The three closed-ended questions revealed high satisfaction among the educators regarding the FDM's effectiveness in breaking down steps into individual activities, promoting mutual understanding between disciplines, and supporting educators in designing activities for cultivating CT skills. Most educators gave the highest score of 5. This indicates that the structured approach of the FDM was well-received and considered effective in supporting educators in designing interdisciplinary experiences for their students.

The open-ended questions provided additional evidence. Educators appreciated the structured sequence of steps, noting that it helped them stay focused and align activities with the project's goals. Additionally, they highlighted the importance of interdisciplinary activities in fostering CT skills. However, they also indicated areas for improvement, particularly the need for clearer guidelines for delineating activities and matching them to CT skills. Educators suggested that while the FDM is flexible and adaptable, providing detailed descriptions and examples could enhance its usability. This feedback can guide further refinements to the methodology, ensuring it meets the diverse needs of educators and students across various educational settings.

Discussion

This paper presented a structured approach for developing interdisciplinary projects that blend ER and Arts to cultivate CT skills. The FDM integrates the structured problem-solving

process by adjusting elements from the CCPS model to enhance students' learning experiences in a blended learning context. Two Artful-ER projects were presented to illustrate the application of the proposed approach. These projects serve as exemplars for educators to follow, demonstrating how the FDM can be implemented to connect ER and Arts, and cultivate CT. These projects' descriptions provide a pathway for educators to design interdisciplinary projects in their own educational settings. The educators who designed and implemented the projects evaluated the proposed approach as well structured and helpful in organizing courses and activities, promoting interdisciplinary collaboration for enhancing students' CT.

Acknowledgements

The European Union's Erasmus+ programme in the context of the project "FERTILE: Artful Educational Robotics to promote Computational Thinking in a Blended Learning Context", grant no 2021-1-EL01-KA220-HED-000023361, co-funded the research. We thank the research teams of the "FERTILE" consortium for contributing to the design of the "FERTILE" Design Methodology and Community Platform and the educators who volunteered to participate in the study.

References

- Bers, M. U. (2018). Coding as a playground: Programming and computational thinking in the early childhood classroom. Routledge.
- Chevalier, M., Giang, C., Piatti, A., & Mondada, F. (2020). Creative computational problem-solving: Model for the 21st century. *Computers & Education*, 148, 103800.
- Ching, Y. H. (2023). Exploring computational thinking through educational robotics. *Journal of Educational Computing Research*, 61(1), 124-145.
- Chookaew, S., Howimanporn, S., & Arayathanitkul, K. (2018). Enhancing computational thinking with educational robotics: A case study of Thai high school students. *International Journal of Emerging Technologies in Learning*, 13(12), 112-122.
- Fronza, I., Pacheco, T., da Rosa Righi, R., & Zorzo, A. F. (2017). Using educational robotics to develop computational thinking skills: A case study with public school students. Brazilian Symposium on Computers in Education (Simpósio Brasileiro de Informática na Educação SBIE).
- Grover, S., & Pea, R. (2013). Computational thinking in K-12: A review of the state of the field. *Educational Researcher*, 42(1), 38-43.
- Istikomah, S. (2018). Educational robotics for promoting computational thinking skills in STEM learning: A review. *Journal of Physics: Conference Series*, 983, 012011.
- Jawawi, R., Isa, W. A. R. W. M., Zainudin, M. F. F., & Rashid, R. A. (2022). Exploring the impact of educational robotics on students' computational thinking skills. *International Journal of Advanced Computer Science and Applications*, 13(5), 123-131.
- Peppler, K. A., & Glosson, D. (2013). Stitching circuits: Learning about circuitry through e-textile materials. *Journal of Science Education and Technology*, 22(5), 751-763.
- Piedade, J. (2020). Exploring computational thinking through robotics activities in primary school. International *Journal of Social, Behavioral, Educational, Economic, Business and Industrial Engineering*, 14(1), 53-57.
- Selby, C., & Woollard, J. (2013). Computational Thinking: The Developing Definition. University of Southampton. Retrieved from https://eprints.soton.ac.uk/356481/
- Souza, M. L. R., Oliveira, E. A., & Fernandes, J. P. (2021). Developing computational thinking with educational robotics: A case study with secondary school students. *International Journal of Advanced Computer Science and Applications*, 12(2), 290-299.
- Vacca, A., Melideo, G., & Tarantino, L. (2021). Art and computational thinking: A promising binomial for teaching STEM. In the *Proceedings of the International Conference on Smart Learning Environments (ICSLE 2021).*

Wing, J. M. (2010). Computational thinking: What and why? The Link Magazine. Retrieved from https://www.cs.cmu.edu/link/research-notebook-computational-thinking-what-and-why